detail and which are participating in an ensemble c
Can we assess our level of doubt? Is possible to as
a nondeterministic agent and, therefore, how much c
certificates?
While in the general case this assessment is difficult
and for nondeterministic agents constructed from co
FSMs, we show here that that the assessment is sim
just relies on high-level summaries of FSM topology,
of the term.
The interesting point of this analysis is that, accordi
theory, it is impossible. For example Nancy Leveson
enemy of reliability" [5]. We disagree: nondetermin

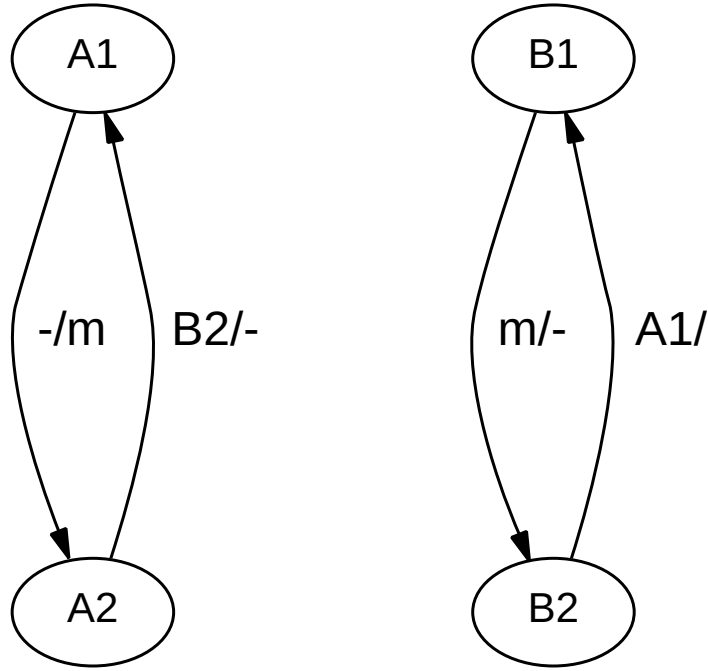
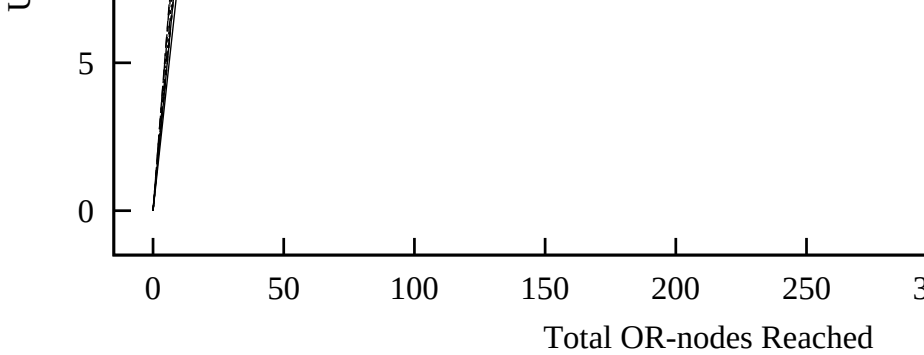
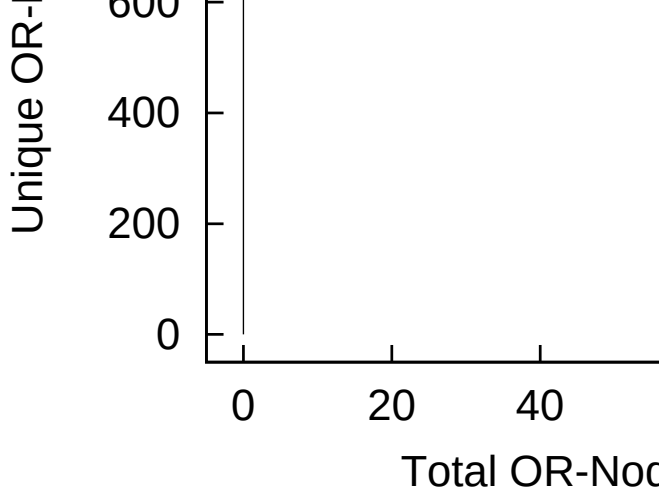


Fig. 1. A system of communicating FSMs (“m



Random search results for model of Dek
two-process mutual exclusion problem
from Holzmann [**?**]). Dots show when a
model is found by the search. The erro
case.

Fig. 2. Random search of AND-OR graphs representing FS



Random search results for a v
FSM model, for which the set
require at most 2.65×10^{178}

Fig. 3. Random search of AND-OR g

cases. To improve our game, we might search for co
frequency. Two such conditions are shown in the WH
shown in Figure 5. In the case of outlook=over
time. In the case of humidity $\leq$ 90, we only pla
one way to play lots of golf would be to select a vac
overcast. While on holidays, one thing to watch for is
then our frequent golf games are threatened.
The tests in the WHERE clause of the select statements
in treatment learning get a score and the learner uses
resulting from *applying a treatment* (i.e. using ther
mode, TAR2 does *controller learning* that finds a t
classes and reject worse classes By reversing the sc

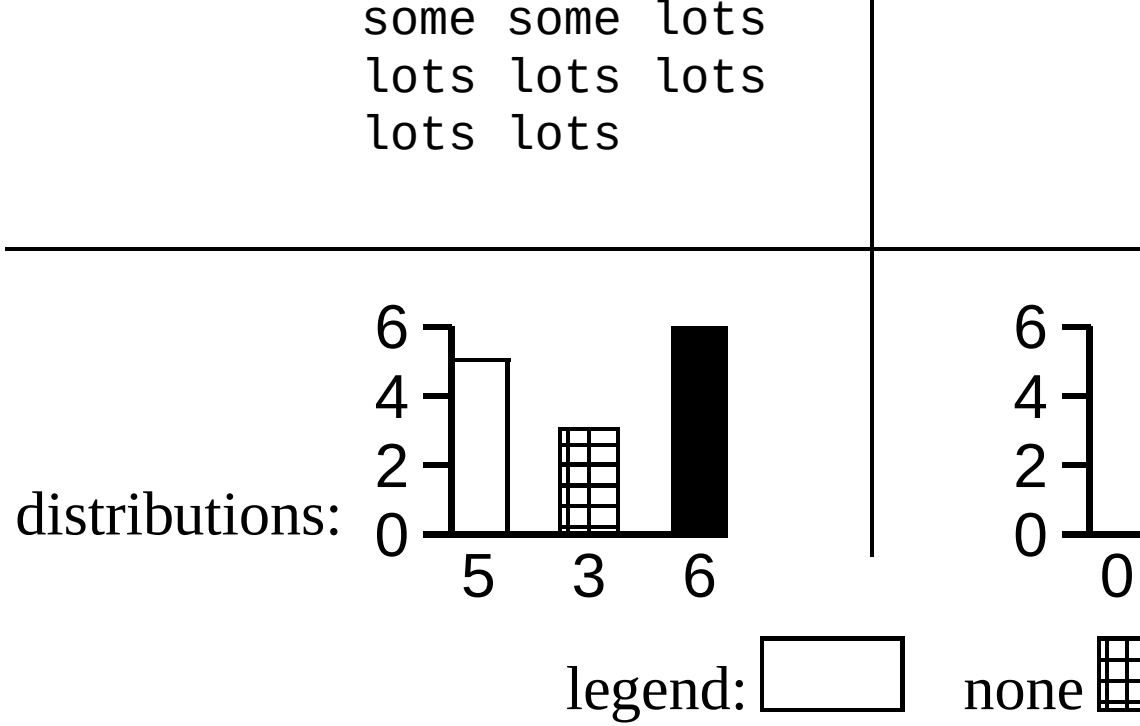
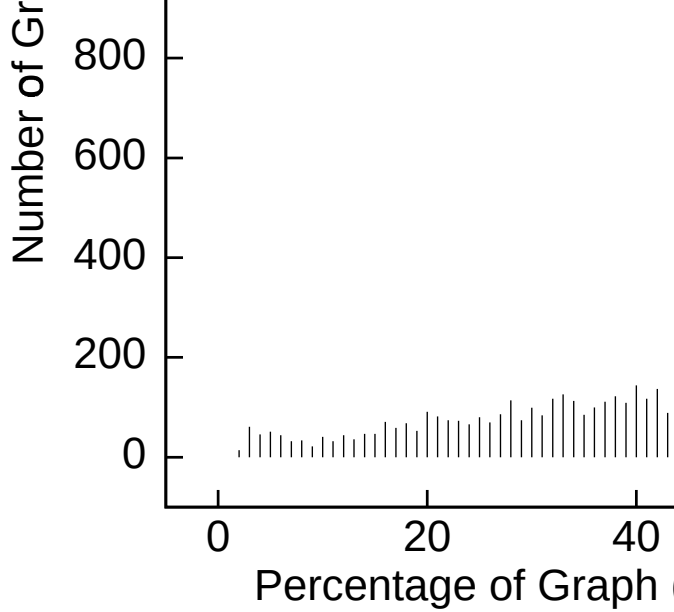


Fig. 5. Class distributions sel

plateau height. We would like to how FSM models
different from FSM models yielding low search pla
the attributes listed above (number of machines, nu
the models with high plateaus represented by the rig
Figure 6?

In our first simple experiment we used TAR2 to de
what range of that attribute, could most significan
plateaus (just like the very simple TAR2 golf exam
we found that restricting *outlook* to *overcast* led to
following treatment: restrict *state inputs* to its highes
what that means, consider Figure 7, which shows the
height (with a dot for each model). On the left, where



Average plateau height = 69.3

Fig. 6. Summary of time-to-plateau (top) and pl

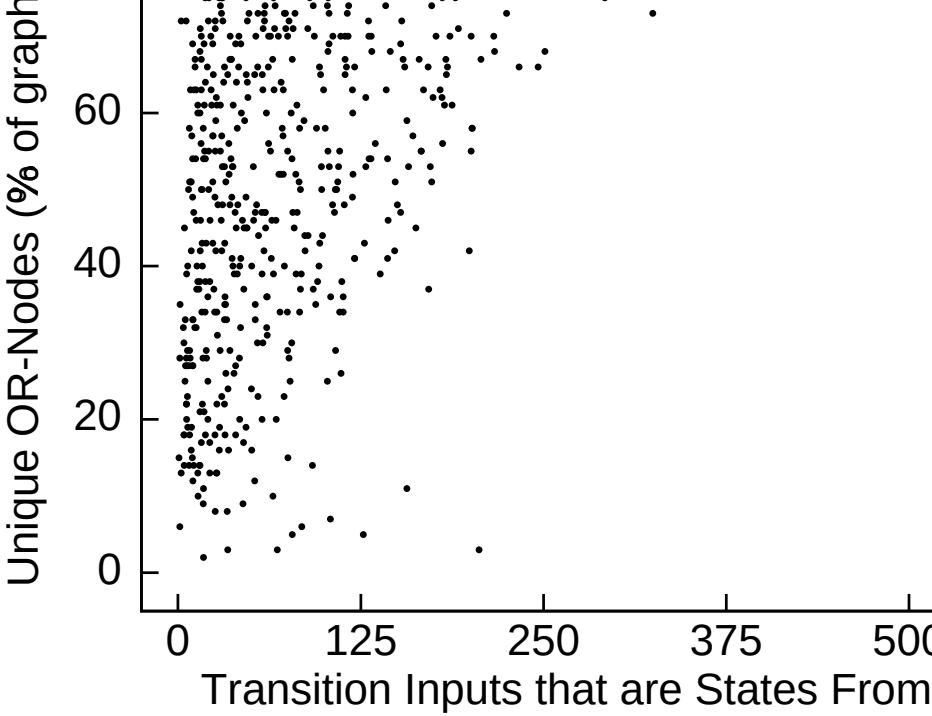


Fig. 7. The number of transition inputs that are states fro

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